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The 35th Chinese Control Conference (CCC2016) will be held Wednesday through Friday, July 27-29, 2016 in Chengdu, China. The CCC is an annual international conference sponsored by the Technical Committee on Control Theory (TCCT), Chinese Association of Automation (CAA). It aims to bring together the international community of systems and control to discuss the latest findings and advances in control theories and technologies. The CCC2016 will feature plenary lectures, contributed and invited papers, panel discussions. pre-conference workshops, oral presentation sessions and interactive sessions. The proceedings of CCC have been included in the IEEE Xplore and indexed by EI Compendex since 2006

Situated in Southwest China, Chengdu, culturally and economically thriving, is one of the most attractive cities and a major metropolis in China. The city, with its rich historical heritage and natural pride, is renowned for its cuisine, tourism, culture, the giant panda, its breathtaking landscape and most welcoming atmosphere. Chengdu is the first Asian city to win a UNESCO City of Gastronomy accolade, one of the six in the world. Welcome to Chenadu! Welcome to CCC2016!

## **Important Dates:**

- 1. Deadline for deadline for all submissions: December 15, 2015
- 2. Deadline for notification of acceptance: April 1, 2016
- 3. Deadline for final submission: April 30, 2016

### **Authors' Information**

- 1. All papers (including proposals of invited sessions) should be submitted online through <a href="http://ccc2016.swjtu.edu.cn">http://ccc2016.swjtu.edu.cn</a> <a href="ccc.amss.ac.cn/2016">ccc.amss.ac.cn/2016</a>
- 2. The CCC2016 presents the Guan Zhao-Zhi Best Paper Award and the Best Poster Award. Detailed application information can be found at http://ccc2016.swjtu.edu.cn ccc.amss.ac.cn/2016
- 3. Invited session proposals should include the following information of all invited papers, such as authors' name and affiliation, the title and the abstract of the paper.

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- S01 Systems Theory and Control Theory
- S02 Nonlinear Systems and Control
- S03 Complexity and Complex System Theory
- S04 Distributed Parameter Systems
- S05 Stability and Stabilization
- S06 Stochastic Systems
- S07 System Modeling and Identification
- S08 Hybrid Systems and Discrete Event **Dynamic Systems**
- S09 Optimal Control
- S10 Optimization and Scheduling
- S11 Robust Control
- S12 Adaptive Control and Learning Control S35 Transportation Systems
- S13 Variable Structure Control
- S14 Neural Networks
- S15 Fuzzy Systems and Fuzzy Control
- S16 Pattern Recognition
- S17 Predictive Control
- S18 Motion Control
- S19 Signal Processing and Information
- S20 Big Data and Cloud Computing
- S21 Navigation and Guidance
- S22 Control Design
- S23 Intelligent Robots and Mechatronic Systems
- S24 Fault Diagnosis and Reliable Control
- S25 Communication Network Systems

- S26 Machine Learning and Artificial Intelligence
- S27 Control of Network Systems and Networked ControlSystems
- S28 Multi-Agent Systems and Distributed Control
- S29 Sensor Networks and Internet of Things
- S30 Green Energy Technology and Control in Energy and Environment
- S31 Vehicle Control
- S32 Data-Driven Modeling and Control
- S33 Micro-Nano and Quantum Systems
- S34 Nature-Inspired Computing
- S36 Systems Biology and Life Systems
- S37 Medical Systems and Automation
- S38 Industrial Systems and Manufacturing
- S39 Systems Engineering Theory and Method
- S40 System Simulation, Integration and **Evaluation**
- S41 Control in Smart Grid S42 Railway Transportation Systems
- S43 Visual Servoing Control
- S44 Game Theory and Social Networks
- S45 Fractional-Order Systems and Control S46 Aircraft Control
- S47 Control Education and Social Impact of
- Automation